

Asia-Pacific Analysis and PDE Seminar

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Joint work with Nader Masmoudi & Tong Yang

Gevrey well-posedness of the 3D Prandtl equations without Structural Assumption

Wei-Xi LI (Wuhan University)

Inviscid limit

Navier-Stokes equation: $\mathbf{u}^\varepsilon = (u_1^\varepsilon, \dots, u_n^\varepsilon)$, $n = 2, 3$

$$\begin{cases} \partial_t \mathbf{u}^\varepsilon + (\mathbf{u}^\varepsilon \cdot \nabla) \mathbf{u}^\varepsilon - \varepsilon \Delta \mathbf{u}^\varepsilon + \nabla p^\varepsilon = 0, \\ \nabla \cdot \mathbf{u}^\varepsilon = 0, \\ \mathbf{u}^\varepsilon|_{t=0} = \mathbf{u}_0, \end{cases}$$

Question: $\mathbf{u}^\varepsilon \rightarrow \mathbf{u}^E$ as $\varepsilon \rightarrow 0$? Here \mathbf{u}^E solves Euler equation

$$\partial_t \mathbf{u}^E + (\mathbf{u}^E \cdot \nabla) \mathbf{u}^E + \nabla p^E = 0, \quad \nabla \cdot \mathbf{u}^E = 0$$

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- ❖ \mathbb{R}^n or **torus**: well-developed
- ❖ **a domain with boundary**: an outstanding open problem

inviscid limit for fluid domain with boundary

Mismatched boundary conditions: $\Omega = \{x_n > 0\}$,

Navier-Stokes: $u^\varepsilon|_{x_n=0} = \mathbf{0}$

Euler: $u^E \cdot \mathbf{n}|_{x_n=0} = u_n^E|_{x_n=0} = 0$

inviscid limit for fluid domain with boundary

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Prandtl' postulate (1908):

$$u^\varepsilon = \begin{cases} u^E + O(\sqrt{\varepsilon}), & \text{outside boundary layer} \\ u^P + O(\sqrt{\varepsilon}), & \text{inside boundary layer} \end{cases}$$

Euler + Prandtl expansion of NS

Question: Euler + Prandtl expansion of Navier-Stokes?

cf. Sammartino-Caflisch, Gérard-Varet, Guo, Iyer, Maekawa, Masmoudi, Nguyen, Wang, Zhang, Yang, Xie, Xin, ...

Goal: Well-posedness for Prandtl system

Derivation of boundary layer equations

Prandtl's ansatz (2D e.g.): $\tilde{y} = y/\sqrt{\varepsilon}$

$$\begin{cases} u^\varepsilon(t, x, y) = u^0(t, x, y) + u^b(t, x, \tilde{y}) + O(\sqrt{\varepsilon}), \\ v^\varepsilon(t, x, y) = v^0(t, x, y) + \sqrt{\varepsilon}v^b(t, x, \tilde{y}) + O(\sqrt{\varepsilon}), \\ p^\varepsilon(t, x, y) = p^0(t, x, y) + O(\sqrt{\varepsilon}), \end{cases}$$

- ❖ Far from the boundary: Euler flow (u^0, v^0, p^0)
- ❖ Inside boundary layer: described by Prandtl equations (u^b, v^b) .

2D Prandtl (scalar) equation

Governing equation for boundary layer: writing $\tilde{y} = y$ for short,

$$\begin{cases} \partial_t u + u \partial_x u + v \partial_y u - \partial_y^2 u + \partial_x p = 0, & x \in \mathbb{R}, y > 0, \\ \partial_x u + \partial_y v = 0, \\ u|_{y=0} = v|_{y=0} = 0, & \lim_{y \rightarrow +\infty} u = U(t, x), \\ u|_{t=0} = u_0, \end{cases}$$

where

$U(t, x), p(t, x)$: givens functions, the trace at $z = 0$ of the tangential velocity and pressure of the Euler flow

3D Prandtl system

(u, v, w) : velocity fields

$$\begin{cases} \partial_t u + (u\partial_x + v\partial_y + w\partial_z)u - \partial_z^2 u + \partial_x p = 0, \\ \partial_t v + (u\partial_x + v\partial_y + w\partial_z)v - \partial_z^2 v + \partial_y p = 0, \\ \partial_x u + \partial_y v + \partial_z w = 0 \\ (u, v, w)|_{z=0} = (0, 0, 0), \quad \lim_{z \rightarrow +\infty} (u, v) = (U, V), \\ u|_{t=0} = u_0, \quad v|_{t=0} = v_0, \end{cases}$$

Main difficulty for Prandtl equation

Loss of derivative coupled with nonlocal property:

$$\mathbf{2D :} \quad \begin{cases} \partial_t u + (u \partial_x + v \partial_y) u - \partial_y^2 u + \partial_x p = 0, \\ v(t, x, y) = - \int_0^y \partial_x u(t, x, r) dr. \end{cases}$$

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$$\mathbf{3D} : \begin{cases} \partial_t u + (u\partial_x + v\partial_y + w\partial_z)u - \partial_z^2 u + \partial_x p = 0, \\ \partial_t v + (u\partial_x + v\partial_y + w\partial_z)v - \partial_z^2 v + \partial_y p = 0, \\ w(t, x, y, z) = - \int_0^z (\partial_x u(t, x, y, r) + \partial_y v(t, x, y, r)) dr. \end{cases}$$

Outlines

Well-posedness for Prandtl equations

Well-posedness for Prandtl equations

Statement of the main result

Methodology

Cancellation mechanism

Abstract Cauchy-Kowalewski theorem

Sobolev well-posedness

2D well-posedness under **Oleinik's monotonicity condition** ($\partial_y u > 0$),

- ❖ Local-in-time solutions: Oleinik, Alexandre-Wang-Xu-Yang(2015), Masmoudi-Wong (2015)
- ❖ Global-in-time Solutions: Zhang-Xin
- ❖ ...

Sobolev well-posedness

2D well-posedness under **Oleinik's monotonicity condition** ($\partial_y u > 0$),

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- ❖ Global-in-time Solutions: Zhang-Xin
- ❖ ...

Sobolev well-posedness for 3D : much less is known!

- ❖ Liu-Wang-Yang (2017): $v(t, x, y, z) = k(t, x, y)u(t, x, y, z)$.
- ❖ weak solutions; Luo-Xin (2018)
- ❖ Global-in-time solution ?

Well-posedness for general data

Function spaces: $x \mapsto f(x)$,

Analytic functions:

$$\sum_{\alpha} \frac{\partial^{\alpha} f(x_0)}{\alpha!} (x - x_0)^{\alpha} < +\infty$$

Gevrey functions:

$$\sum_{\alpha} \frac{\partial^{\alpha} f(x_0)}{(\alpha!)^{\sigma}} (x - x_0)^{\alpha} < +\infty$$

Analytic space \subset Gevrey class space $\subset C^{\infty}$

Gevrey (analytic) well-posedness

Without structural assumption: critical Gevrey index 2 .

Gevrey ill-posedness for index > 2 :

- ✦ Gérard-Vare and Dormy(2010, 2D), Liu-Wang-Yang (2016, 3D)

Gevrey (analytic) well-posedness

Without structural assumption: critical Gevrey index 2 .

Gevrey ill-posedness for index > 2 :

- ❖ Gérard-Vare and Dormy(2010, 2D), Liu-Wang-Yang (2016, 3D)

Gevrey well-posedness for index ≤ 2 :

- ❖ Analytic space: Sammartino-Caflisch(1998), 2D & 3D ,
- ❖ Sharp Gevrey space: Dietert-Gérard-Vare (2019, 2D); $3D?$
- ❖ Global solutions: Paicu-Zhang (analytic,2D,2020), Wang-Wang-Zhang (Gevrey, 2D, 2021); $3D?$

Outlines

Well-posedness for Prandtl equations

Main result: Gevery well-posed for 3D Prandtl

Statement of the main result

Methodology

Cancellation mechanism

Abstract Cauchy-Kowalewski theorem

3D Prandtl

3D Prandtl :

$$\left\{ \begin{array}{l} \partial_t u + (u\partial_x + v\partial_y + w\partial_z)u - \partial_z^2 u = 0, \\ \partial_t v + (u\partial_x + v\partial_y + w\partial_z)v - \partial_z^2 v = 0, \\ \partial_x u + \partial_y v + \partial_z w = 0 \\ (u, v, w)|_{z=0} = (0, 0, 0), \quad \lim_{z \rightarrow +\infty} (u, v) = (0, 0), \\ u|_{t=0} = u_0, \quad v|_{t=0} = v_0, \end{array} \right.$$

Assumption

Suppose $(u_0, v_0) \in X_{\rho_0, \sigma}$ for $1 < \sigma \leq 2$, where we say $(u, v) \in X_{\rho, \sigma}$ if

$$\begin{aligned} \|(u, v)\|_{\rho, \sigma} = & \sup_{\substack{0 \leq j \leq 5 \\ |\alpha| + j \geq 7}} \frac{\rho^{|\alpha| + j - 7}}{[(|\alpha| + j - 7)!]^\sigma} \|\langle z \rangle^{\ell + j} \partial_{x, y}^\alpha \partial_z^j (u, v)\|_{L^2} \\ & + \sup_{\substack{0 \leq j \leq 5 \\ |\alpha| + j \leq 6}} \|\langle z \rangle^{\ell + j} \partial_{x, y}^\alpha \partial_z^j (u, v)\|_{L^2}. \end{aligned}$$

where $\ell > 1/2$ and $\langle z \rangle = (1 + |z|^2)^{1/2}$

Well-posedness in Gevrey class

Theorem (L.-Masmoudi-Yang)

Suppose $(u_0, v_0) \in X_{\rho_0, \sigma}$ for $1 < \sigma \leq 2$, compatible with boundary conditions. Then the 3D Prandtl system admits a unique solution $(u, v) \in L^\infty([0, T]; X_{\rho, \sigma})$ for some $T > 0$ and some $0 < \rho < \rho_0$.

Outlines

Well-posedness for Prandtl equations

Statement of the main result

Proof of the main result

Methodology

Cancellation mechanism

Abstract Cauchy-Kowalewski theorem

Methodology

Cancellation mechanism + Abstract Cauchy-Kowalewski (ACK) theorem

Outlines

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Intrinsic cancellation law

Observe, applying ∂_x to eq. $(\partial_t + u\partial_x + v\partial_y - \partial_y^2)u = 0$,

$$(\partial_t + u\partial_x + v\partial_y - \partial_y^2)\partial_x u = -(\partial_y u)\partial_x v(t, x, y) - (\partial_x u)^2$$

with bad term $\partial_x v$

Auxilliary function \mathcal{U} , inspired by Dietert and Gérard-Varet [Annals of PDE (2019)],

$$\begin{cases} (\partial_t + u\partial_x + v\partial_y - \partial_y^2) \int_0^y \mathcal{U}(t, x, r) dr = -\partial_x v(t, x, y), \\ \mathcal{U}|_{t=0} = 0, \quad \partial_y \mathcal{U}|_{y=0} = \mathcal{U}|_{y \rightarrow +\infty} = 0. \end{cases}$$

Intrinsic cancellation law

$$\begin{cases} (\partial_t + u\partial_x + v\partial_y - \partial_y^2) \int_0^y \mathcal{U}(t, x, r) dr = -\partial_x v(t, x, y), \\ (\partial_t + u\partial_x + v\partial_y - \partial_y^2) \partial_x u = -(\partial_y u) \partial_x v(t, x, y) - (\partial_x u)^2. \end{cases}$$

cancellation
 \implies

$$\begin{aligned} \lambda &= \partial_x u - (\partial_y u) \int_0^y \mathcal{U}(t, x, r) dr; \\ (\partial_t + u\partial_x + v\partial_y - \partial_y^2) \lambda &= l.o.t. \end{aligned}$$

Estimate on $\lambda \implies$ Estimate on $\partial_x u$?

$$\int_0^y \mathcal{U}(t, x, r) dr \text{ by estimating } \mathcal{U}$$

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Abstract Cauchy-Kowalewski theorem

A toy model:

$$\begin{cases} \partial_t \vec{h} = F(t, \partial_x \vec{h}), \\ \vec{h}|_{t=0} = \vec{h}_0. \end{cases} \quad (1)$$

A key estimate: $\forall \rho < \tilde{\rho}$,

$$|\vec{h}(t)|_\rho^2 \leq |\vec{h}_0|_\rho^2 + C \int_0^t \frac{|\vec{h}(s)|_{\tilde{\rho}(s)}^2}{\tilde{\rho}(s) - \rho} ds,$$

where $|\vec{h}|_\rho = \sup_{k \geq 0} \frac{\rho^k}{k!} \|\partial_x^k \vec{h}\|_{L^2}$.

Conclusion: The Cauchy problem (1) admits a unique local solution in $L^\infty([0, T]; X_\rho)$, provided $\vec{h}_0 \in X_{\rho_0}$

ACK Theorem for Gevery space

Model:

$$\begin{cases} \partial_t^2 \vec{h} = F(t, \partial_x \vec{h}), \\ \vec{h}|_{t=0} = \vec{h}_0, \quad \partial_t \vec{h}|_{t=0} = \vec{h}_1. \end{cases} \quad (2)$$

A key estimate: $\forall \rho < \tilde{\rho}$,

$$|\vec{b}(t)|_\rho^2 \leq |\vec{b}_0|_\rho^2 + C \int_0^t \frac{|\vec{b}(s)|_{\tilde{\rho}(s)}^2}{\tilde{\rho}(s) - \rho} ds, \quad \vec{b} := (\vec{h}, \partial_t \vec{h})$$

where $|\vec{b}|_\rho = \sup_{k \geq 0} \frac{\rho^k}{(k!)^2} \|\partial_x^k \vec{h}\|_{L^2} + \sup_{k \geq 0} \frac{\rho^{k+1}}{(k+1)!^2} k \|\partial_x^k \partial_t \vec{h}\|_{L^2}$.

Conclusion: The Cauchy problem (2) admits a unique local solution in $L^\infty([0, T]; X_\rho)$, provided $\vec{h}_0, \vec{h}_1 \in X_{\rho_0}$

Proof of ACK for Gevrey space

Denote $\vec{\xi} = \partial_t \vec{h}$.

$$\begin{cases} \partial_t^2 \vec{h} = F(t, \partial_x \vec{h}), \\ \vec{h}|_{t=0} = \vec{h}_0, \quad \partial_t \vec{h}|_{t=0} = \vec{h}_1. \end{cases} \implies \begin{cases} \partial_t \vec{\xi} = F(t, \partial_x \vec{h}), \\ \partial_t \vec{h} = \vec{\xi}, \\ (\vec{h}, \vec{\xi})|_{t=0} = (\vec{h}_0, \vec{h}_1). \end{cases}$$

This suggests $\vec{\xi} \approx |D_x|^{1/2} h$. Recall

$$|\vec{b}|_\rho = \sup_{k \geq 0} \frac{\rho^k}{k!^2} \|\partial_x^k \vec{h}\|_{L^2} + \sup_{k \geq 0} \frac{\rho^{k+1}}{[(k+1)!]^2} k \|\partial_x^k \vec{\xi}\|_{L^2}.$$

ACK for general model

$$\partial_t^2 \vec{h} = F(t, \partial_x \vec{h}) \xrightarrow{\text{more general}} \underbrace{(\partial_t + u\partial_x + v\partial_y - \partial_y^2)^2}_{\text{Prandtl operator}} \vec{h} = F(t, \partial_x \vec{h}).$$

Estimate on auxillary function \mathcal{U}

$$\begin{cases} (\partial_t + u\partial_x + v\partial_y - \partial_y^2) \int_0^y \mathcal{U}(t, x, r) dr = -\partial_x v(t, x, y), \\ (\partial_t + u\partial_x + v\partial_y - \partial_y^2) \partial_x u = -(\partial_y u) \partial_x v(t, x, y) - (\partial_x u)^2. \end{cases}$$

cancellation
 \implies

$$\begin{aligned} \lambda &= \partial_x u - (\partial_y u) \int_0^y \mathcal{U}(t, x, r) dr; \\ (\partial_t + u\partial_x + v\partial_y - \partial_y^2) \lambda &= l.o.t. \end{aligned}$$

Estimate on $\lambda \implies$ Estimate on $\partial_x u$?

$$\int_0^y \mathcal{U}(t, x, r) dr \text{ by estimating } \mathcal{U}$$

Estimate on auxillary function \mathcal{U}

$$(\partial_t + u\partial_x + v\partial_y - \partial_y^2) \int_0^y \mathcal{U}(t, x, r) dr = -\partial_x w.$$

$$\Rightarrow \begin{cases} (\partial_t + u\partial_x + v\partial_y - \partial_y^2)\mathcal{U} = \partial_x \lambda + l.o.t. \\ (\partial_t + u\partial_x + v\partial_y - \partial_y^2)\partial_x \lambda = \text{terms of order } \leq 2 \end{cases}$$

$$\Rightarrow (\partial_t + u\partial_x + v\partial_y - \partial_y^2)^2 \mathcal{U} = \text{terms of order } \leq 2 + l.o.t.$$

Conclusion: Estimate \mathcal{U} in Gevrey space ≤ 2 , applying ACK theorem for $(\partial_t + u\partial_x + v\partial_y - \partial_y^2)^2 \vec{h} = F(t, \partial_x \vec{h})$

A priori estimate

$\forall (\rho, \tilde{\rho})$ with $0 < \rho < \tilde{\rho} < \rho_0$ and $\forall t \in [0, T]$.

$$|\vec{a}(t)|_{\rho, \sigma}^2 \leq C \|u_0\|_{\rho_0, \sigma}^2 + C \left(\int_0^t (|\vec{a}(s)|_{\rho, \sigma}^2 + |\vec{a}(s)|_{\rho, \sigma}^4) ds + \int_0^t \frac{|\vec{a}(s)|_{\tilde{\rho}, \sigma}^2}{\tilde{\rho} - \rho} ds \right),$$

where $\vec{a} = (u, \mathcal{U}, \lambda)$ and

$$|\vec{a}|_{\rho, \sigma} = \sup_{\substack{0 \leq j \leq 5 \\ m+j \geq 7}} \frac{\rho^{m+j-7}}{[(m+j-7)!]^\sigma} \|\langle y \rangle^{\ell+j} \partial_x^m \partial_y^j u\|_{L^2} \\ + \sup_{m \geq 6} \frac{\rho^{m-6}}{[(m-6)!]^\sigma} \|\partial_x^m \mathcal{U}\|_{L^2} + \sup_{m \geq 6} \frac{\rho^{m-6}}{[(m-6)!]^\sigma} m \|\partial_x^m \lambda\|_{L^2}.$$

3D counterparts: auxiliary functions

$$\begin{cases} (\partial_t + u\partial_x + v\partial_y + w\partial_z - \partial_z^2) \int_0^z \mathcal{U}(t, x, y, \tilde{z}) d\tilde{z} = -\partial_x w(t, x, y, z), \\ \mathcal{U}|_{t=0} = 0, \quad \partial_z \mathcal{U}|_{z=0} = \mathcal{U}|_{z \rightarrow +\infty} = 0. \end{cases}$$

and

$$\begin{cases} (\partial_t + u\partial_x + v\partial_y + w\partial_z - \partial_z^2) \int_0^z \tilde{\mathcal{U}}(t, x, y, \tilde{z}) d\tilde{z} = -\partial_y w(t, x, y, z), \\ \tilde{\mathcal{U}}|_{t=0} = 0, \quad \partial_z \tilde{\mathcal{U}}|_{z=0} = \tilde{\mathcal{U}}|_{z \rightarrow +\infty} = 0. \end{cases}$$

3D counterparts: auxiliary functions

$$\begin{cases} \lambda = \partial_x u - (\partial_z u) \int_0^z \mathcal{U} d\tilde{z}, & \tilde{\lambda} = \partial_y u - (\partial_z u) \int_0^z \tilde{\mathcal{U}} d\tilde{z}, \\ \delta = \partial_x v - (\partial_z v) \int_0^z \mathcal{U} d\tilde{z}, & \tilde{\delta} = \partial_y v - (\partial_z v) \int_0^z \tilde{\mathcal{U}} d\tilde{z}, \end{cases}$$

Thanks for your attention!