

Last time - integrating vector fields over surfaces.

- $\iint_S \vec{F} \cdot d\vec{S} := \iint_S \vec{F} \cdot \hat{\vec{n}} dS$

- if  $\vec{r}(u,v)$ ,  $(u,v) \in D$  is a parametrization of  $S$  and  $\vec{r}_u \times \vec{r}_v$  is positively oriented, then

$$\iint_S \vec{F} \cdot d\vec{S} = \iint_D \vec{F}(\vec{r}(u,v)) \cdot (\vec{r}_u \times \vec{r}_v) dA$$

- Let  $S = \{3x + 2y + z = 1, x \geq 0, y \geq 0, z \geq 0\}$   
oriented upward.

$S$  is parametrized by  $\vec{r}(u,v) = \langle u, v, 1 - 3u - 2v \rangle$

where  $(u,v) \in D = \{u \geq 0, v \geq 0, 3u + 2v \leq 1\}$ .

- Is  $\vec{r}_u \times \vec{r}_v$  positively oriented?
- use this to calculate  $\iint_S \vec{F} \cdot d\vec{S}$  where  $\vec{F}(x,y,z) = \langle 1, 0, 1 \rangle$ .  
[see slides]

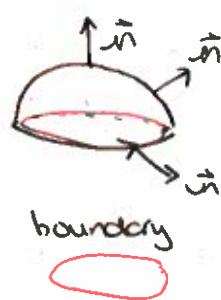
Today: Stoke's theorem: §16.8

Let  $S$  be an oriented surface.

The **boundary curve**  $\partial S$  of  $S$  is the set of points that

- nearly,  $S$  looks like  $\{y\} \times \mathbb{R}^2$  (instead of  $\mathbb{R}^2$ ).

Examples.



The orientation on  $\hat{\vec{n}}$  induces an orientation on the boundary

- point your head in the direction of  $\hat{\vec{n}}$
- orient  $\partial S$  so that  $S$  is to your left as you walk along  $\partial S$

- Assumptions:
- $S$  is "nice"
  - $S$  is piecewise smooth
  - $\partial S$  is one or more simple closed paths.
  - $\vec{F}$  has continuous first order partial derivatives on an open region  $R \subset \mathbb{R}^3$  containing  $S$ .

135.2

Stokes' Theorem:

$$\iint_S \operatorname{curl} \vec{F} \cdot d\vec{S} = \oint_{\partial S} \vec{F} \cdot d\vec{r}$$

↓  
 derivative      ↓  
 boundary.

- use this to integrate  $\operatorname{curl} \vec{F}$  over  $S$  if  $\partial S$  is simpler than  $S$  or to integrate  $\vec{F}$  over  $\partial S$  if  $\operatorname{curl} \vec{F}$  is simpler.

Why?

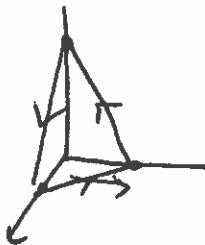
- Fundamental theorem of calculus.

Example: Let  $\vec{F} = \langle 1, x + \sin y^2, y - e^{z^3} \rangle$

$$S = \{3x + 2y + z = 1, x \geq 0, y \geq 0, z \geq 0\}.$$

oriented upwards.

$$C = \partial S. \quad \text{Find } \oint_C \vec{F} \cdot d\vec{r}.$$



Stokes' theorem:

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_S \operatorname{curl} \vec{F} \cdot d\vec{S}$$

$$\operatorname{curl} \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 1 & x + \sin y^2 & y - e^{z^3} \end{vmatrix} = \hat{i}(1-0) - \hat{j}(0-0) + \hat{k}(1-0) = \langle 1, 0, 1 \rangle.$$

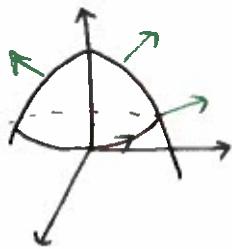
simpler than  $\vec{F}$ !

But we already calculated the integral

of  $\times \vec{G} = \langle 1, 0, 1 \rangle$  over  $S$  in the first example:  $\frac{1}{3}$ .

Example:  $\vec{F} = \langle y, -x, xe^{y^2} \rangle$ ,  $S = \{z = 10 - x^2 - y^2 \text{ and } z \geq 1\}$   
oriented upwards.

Find  $\iint_S \operatorname{curl} \vec{F} \cdot d\vec{S}$ .



$$\partial S = f_1 = 10 - x^2 - y^2 \uparrow.$$

$$x^2 + y^2 = 9 \quad \text{oriented counter-clockwise}.$$

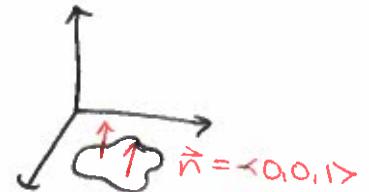
$\hookrightarrow$  parametrization  $\vec{r}(t) = \langle 3\cos t, 3\sin t, 1 \rangle$ ,  $0 \leq t \leq 2\pi$ .  
(matching orientation).

Stokes' Theorem:

$$\begin{aligned} \iint_S \operatorname{curl} \vec{F} \cdot d\vec{S} &= \int_{\partial S} \vec{F} \cdot d\vec{r} \\ &= \int_0^{2\pi} \vec{F}(\vec{r}(t)) \cdot \vec{r}'(t) dt \\ &= \int_0^{2\pi} \langle 3\sin t, -3\cos t, 3\cos t e^{3\sin^2 t} \rangle \cdot \langle -3\sin t, 3\cos t, 0 \rangle dt \\ &= \int_0^{2\pi} -9 dt = -18\pi. \end{aligned}$$

Example Assume  $\vec{F} = \langle P(x,y), Q(x,y), 0 \rangle$  and  $S \subset \{z=0\}$ , oriented upward.

$$\begin{aligned} \iint_{\partial S} P dx + Q dy &= \iint_S \vec{F} \cdot d\vec{r} = \iint_S (\operatorname{curl} \vec{F}) \cdot d\vec{S} \\ &= \iint_S (\operatorname{curl} \vec{F}) \cdot \hat{n} dS \\ &= \iint_S \langle 0, 0, Q_x - P_y \rangle \cdot \hat{k} dS \\ &= \iint_S Q_x - P_y dA. \end{aligned}$$



$\hookrightarrow$  this is Green's Theorem!

Q. Let  $\vec{F} = \langle x\sin z, y\sin z, e^{x+y} \rangle$  and  $S = \{x^2 + y^2 + z^2 = 9\}$  oriented outwards.

Find  $\iint_S \operatorname{curl} \vec{F} \cdot d\vec{S}$ .

### § CURL.

Let  $C$  be an oriented curve with unit tangent vector  $\vec{T}$ .

Recall: The circulation of  $\vec{F}$  around  $C$  is

$$\int_C \vec{F} \cdot \vec{T} ds = \int_C \vec{F} \cdot d\vec{r}.$$

It measures if fluid flows with C or against C. [35.4]

Look so that a unit vector  $\vec{v}$  points towards you.

Place a tiny paddle wheel on S with normal  $\vec{v}$



By Stokes' Theorem, the circulation around

$\partial S$  is

$$\begin{aligned} \int_{\partial S} \vec{F} \cdot d\vec{r} &= \iint_S (\text{curl } \vec{F}) \cdot \vec{v} \, dS \\ &= \iint_S (\text{curl } \vec{F}) \cdot \vec{v} \, dS \end{aligned}$$

So: the paddle wheel

- rotates counterclockwise  $\Leftrightarrow (\text{curl } \vec{F}) \cdot \vec{v} > 0$
- rotates clockwise  $\Leftrightarrow (\text{curl } \vec{F}) \cdot \vec{v} < 0$ .
- $|\text{curl } \vec{F} \cdot \vec{v}|$  gives speed of rotation.
  - doesn't rotate  $\Leftrightarrow \text{curl } \vec{F} \cdot \vec{v} = 0$
  - fastest speed of rotation is when  $\vec{v} = \pm \text{curl } \vec{F}$ .